## Multiple Choice Questions BCA

## **Data Structure and Algorithm Analysis**

1.	If all $c(i, j)$ 's and $r(i, j)$ 's are calculated, then OBST algorithm in worst case takes one of the following time.
	(a) $O(n \log n)$ (b) $O(n^3)$ (c) $O(n^2)$ (d) $O(\log n)$ (e) $O(n^4)$ .

Ans:  $O(n^3)$ 

2. For a 15-puzzle problem let the initial arrangement be the following one, then answer the questions 4-7 with the following arrangement.

10	13	15	7
9	1	4	14
12		8	6
11	2	5	3

What is the value of 'x' used to find the reachability of the solution?
(a) 1 (b) 0 (c) 8 (d) 10 (e) 13.

Ans:1

3. The upper bound on the time complexity of the nondeterministic sorting algorithm is

(a) O(n) (b)  $O(n \log n)$  (c) O(1) (d)  $O(\log n)$  (e)  $O(n^2)$ .

Ans: O(n)

4. The worst case time complexity of the nondeterministic dynamic knapsack algorithm is

(a)  $O(n \log n)$  (b)  $O(\log n)$  (c)  $O(n^2)$  (d) O(n) (e) O(1).

Ans:O(n)

5. Recursive algorithms are based on

(a) Divideand conquer approach (b) Top-down approach

(c) Bottom-up approach (d) Hierarchical approach

(e) Heuristic approach.

Ans :Bottom-up approach

6. What do you call the selected keys in the quick sort method?

(a) Outer key (b)Inner Key (c) Partition key(d) **Pivot key** (e) Recombine key. Ans:

7. How do you determine the cost of a spanning tree?

(a) By the sum of the costs of the edges of the tree

(b) By the sum of the costs of the edges and vertices of the tree

(c) By the sum of the costs of the vertices of the tree

(d) By the sum of the costs of the edges of the graph

(e) By the sum of the costs of the edges and vertices of the graph.

Ans :By the sum of the costs of the edges of the tree

8. The time complexity of the normal quick sort, randomized quick sort algorithms in the worst case is (a) O(n²), O(n log n) (b) O(n²), O(n²) (c) O(n log n), O(n²) (d)	
$O(n \log n), O(n \log n)$ (e) $O(n \log n), O(n^2 \log n)$ .	
Ans : $O(n^2)$ , $O(n^2)$	
<ul> <li>9. Let there be an array of length 'N', and the selection sort algorithm is used to sort it how many times a swap function is called to complete the execution?</li> <li>(a) N log N times</li> <li>(b) log N times</li> <li>(c) N² times</li> <li>(d) N-1 times</li> <li>(e) N times.</li> </ul>	,
Ans :N-1 times	
<ul> <li>10. The Sorting methodwhich is used for external sort is</li> <li>(a) Bubble sort (b) Quick sort (c) Merge sort</li> <li>(d) Radix sort (e) Selection sort.</li> </ul>	
Ans :Radix sort	
<ul> <li>11. In analysis of algorithm, approximate relationship between the size of the job and the amount of work required to do is expressed by using</li></ul>	ł
Ans:Order of execution	
<ul> <li>12. Worst case efficiency of binary search is</li> <li>(a) log<sub>2</sub> n + 1</li> <li>(b) n</li> <li>(c) N<sup>2</sup></li> <li>(d) 2<sup>n</sup></li> <li>(e) log n.</li> </ul>	
Ans: $\log_2 n + 1$	
13. For defining the best time complexity, let $f(n) = \log n$ and $g(n) = \sqrt{n}$ ,	_
Ans : $f(n) \notin \Omega(g(n))$ , but $g(n) \in \Omega(f(n))$	
14. For analyzing an algorithm, which is better computing time?	
(a)O (100 Log N) (b) O (N) (c)O ( $2^{N}$ ) (d) O (N log N) (e) O ( $N^{2}$ ).	
Ans :O (100 Log N)	

16. Consider the usual algorithm for determining whether a sequence of parentheses is balanced. What is the maximum number of parentheses that will appear on the stack AT ANY ONE TIME when the algorithm analyzes: (()(())(())) (a) 1 (b)2 (c)3 (d) 4
Ans:3
<ul> <li>17. Breadth first search</li></ul>
Ans :Scans all incident edges before moving to other node.
<ul><li>18. Which method of traversal does not use stack to hold nodes that are waiting to be processed?</li><li>(a) Dept First (b) D-search (c)Breadth first (d) Back-tracking</li></ul>
Ans :Breadth first
19. The Knapsack problem where the objective function is to minimize the profit is
(a) Greedy (b) Dynamic o / 1 (c) Back tracking (d) Branch & Bound o/1
Ans :Branch & Bound o/1
20. Choose the correct answer for the following statements:  I. The theory of NP-completeness provides a method of obtaining a polynomial time for NPalgorithms.  II. All NP-complete problem are NP-Hard.  (a) I is FALSE and II is TRUE (b) I is TRUE and II is FALSE  (c) Both are TRUE (d) Both are FALSE
Ans :I is FALSE and II is TRUE
<ul> <li>21. The Hamiltonian cycles problem uses the following line of code to generate a next vertex, provided x[] is a global array and k<sup>th</sup> vertex is under consideration:</li> <li>(a) x[k] ← (x[k] + 1) mod n (b) x[k] ← (x[k]) mod (n)</li> <li>(c) x[k] ← (x[k] + 1) mod (n+1) (d) x[k] ← x[k+1] mod n</li> </ul>
Ans $:x[k] \leftarrow (x[k] + 1) \mod (n+1)$
22. The graph colouringalgorithm's time can be bounded by (a) $O(mn^m)$ (b) $O(n^m)$ (c) $O(n^m \cdot 2^n)$ (d) $O(nm^n)$ .
Ans :O(nm <sup>n</sup> ).
23. For 0/1 KNAPSACK problem, the algorithm takes amount of time for

memory table, and time to determine the optimal load, for N objects and W as the capacity of KNAPSACK. (a) O(N+W), O(NW) (b)  $\theta(NW)$ , O(N+W) (c) O(N), O(NW) (d) O(NW), O(N)Ans :(b)  $\theta$ (NW),O(N+W) 24. Sorting is not possible by using which of the following methods? (b) Selection (c) Deletion (d) Exchange (a) Insertion Ans: Deletion 25. What is the type of the algorithm used in solving the 8 Queens problem? (a)Backtracking (b) Dynamic (c) Branch and Bound (d) DandC Ans: Backtracking 26. The following are the statements regarding the NP problems. Chose the **right** option from the following options: I. All NP-complete problems are not NP-hard. SomeNP-hard problems are not known to be NP-complete. II. (a) Both (I) and (II) are true Both (I) and (II) are false (b) (c) Only (I) is true (d) Only (II) is true Ans :Only (II) is true 27. Let G be a graph with 'n' nodes and let 'm' be the chromatic number of the graph. Then the time taken by the backtracking algorithm to color it is (a) O(nm) (b) O(n+m)O(mn<sup>m</sup>) (c) (d)  $O(nm^n)$ . Ans  $:O(nm^n)$ . 28. The time complexity of the shortest path algorithm can be bounded by  $O(n^2)$ (a)  $O(n^4)$ (b) (c)  $O(n^3)$ (d) O(n)(e)  $O(n \log n)$ . Ans: $O(n^3)$ 29. Read the following statements carefully and pick the **correct** option: I. The worst time complexity of the Floyd's algorithm is  $O(n^3)$ . II. The worst time complexity of the Warshall's algorithm is  $O(n^3)$ .

(I) is false but (II) is true

(I) is true but (II) is false

Both (I) and (II) are true

(I) is true and (II) is not true always

(a)

(b)

(c) (d) (e) Both (I) and (II) are false.

Ans: Both (I) and (II) are true

- 30. The asymptotic notation for defining the average time complexity is
  - (a) Equivalence
  - (b) Symmetric
  - (c) Reflexive
  - (e) Both (c) and (d) above.

## Ans: Equivalence

- 31. For the bubble sort algorithm, what is the time complexity of the best/worst case? (assume that the computation stops as soon as no more swaps in one pass)
  - (a) best case: O(n) worst case: O(n\*n)
  - (b) best case: O(n) worst case: O(n\*log(n))
  - (c) best case: O(n\*log(n)) worst case: O(n\*log(n))
  - (d) best case: O(n\*log(n)) worst case: O(n\*n)

Ans: best case: O(n) worst case: O(n\*n)

- 32. For the quick sort algorithm, what is the time complexity of the best/worst case?
  - (a) best case: O(n) worst case: O(n\*n)
  - (b) best case: O(n) worst case: O(n\*log(n))
  - (c) best case: O(n\*log(n)) worst case: O(n\*log(n))
  - (d) best case: O(n\*log(n)) worst case: O(n\*n)

Ans :best case: O(n\*log(n)) worst case: O(n\*n)

- 33. In an arbitrary tree ( not a search tree) of order M. Its size is N, and its height is K. The computation time needed to find a data item on T is
  - (a) O(K\*K)
  - (b) O(M\*M)
  - (c) O(N)
  - (d) O(K)

Ans: O(N)

- 34. Which of the following belongs to the algorithm paradigm?
  - (a) Minimum & Maximum problem
  - (b) Knapsack problem
  - (c) Selection problem
  - (d) Merge sort
  - (e) Quick sort.

Ans: Knapsack problem

- 35. If f,t:  $N \rightarrow R^+$ , then t (n)  $\in \Omega$  (f (n)), iff f(n)  $\in O$  (t (n)) is known as
  - (a) Limit rule
  - (b) Rule of inference
  - (c) Duality rule
  - (d) Rule of consequences

36. The	time taken by NP-class sorting algorithm is
-	O(1)
(b)	O(log n)
(c)	$O(n^2)$
(d)	O(n)

Ans:O(n)

- 37. Find the odd one out from the following categories of algorithms.
  - (a) TVSP
  - (b) N-Queens
  - (c) 15-Puzzle
  - (d) Bin-Packing.

Ans: Bin-Packing.

- 38. The time complexity of binary search in best, worst cases for an array of size N is
  - (a)  $N, N^2$
  - (b) 1, Log N
  - (c)  $\log \bar{N}, N^2$
  - (d) 1, N log N

Ans: 1, Log N

- 39. Which of following algorithm scans the list by swapping the entries whenever pair of adjacent keys are out of desired order?
  - (a) Insertion sort
  - (b) Quick sort
  - (c) Shell sort
  - (d) Bubble sort

Ans: Bubble sort

- 40. The mathematical definition for Omega can be defined as, provided f,g:N $\rightarrow$ R<sup>+</sup> and c is a positive constant and n > n<sub>0</sub>,
  - (a)  $f(n) \ge c. g(n) n$
  - (b) f(n) = c. g(n) n
  - (c)  $f(n) \ge c + g(n) n$
  - (d) f(n) = c + g(n) n

Ans:  $f(n) \ge c$ . g(n) n

- 41. The  $\theta$  notation is
  - (a) Symmetric
  - (b) Reflexive
  - (c) Transitive
  - (d) (a), (b) and (c) above.

Ans: (a), (b) and (c) above.

- 42 From the following choose the one which belongs to the algorithm paradigm other than . to which others from the following belongs to.
  - (a) Minimum & Maximum problem
  - (b) Knapsack problem
  - (c) Selection problem
  - (d) Merge sort

Ans: Knapsack problem

- 43 Pick the **correct** statement(s) from the following set of statements.
  - I. In the Kruskal's algorithm, for the construction of minimal spanning tree for a graph, the selected edges always form a forest.
  - II. In Prim's algorithm, for the construction of minimal spanning tree for a graph, the selected edges always form an orchard.
  - III. DFS, BFS algorithms always make use of a queue, and stack respectively.
  - (a) Only (I) above
  - (b) Only (II) above
  - (c) Only (III) above
  - (d) Both (I) and (III) above

Ans: Only (I) above

- 44. Identify the name of the sorting in which time is not proportional to  $n^2$ .
  - (a) Selection sort
  - (b) Bubble sort
  - (c) Qucik sort
  - (d) Insertion sort.

Ans: Insertion sort

- 45. The optimal solution to a problem is a combination of optimal solutions to its subproblems. This is known as
  - (a) Principle of Duality
  - (b) Principle of Feasibility
  - (c) Principle of Optimality
  - (d) Principle of Dynamicity.

Ans: Principle of Optimality

- 46. Which of the following versions of merge sort algorithm does uses space efficiently?
  - (a) Contiguous version
  - (b) Array version
  - (c) Linked version
  - (d) Structure version
  - (e) Heap version.

Ans: Linked version

- 47. Identify the correct problem for multistage graph from the list given below.
  - (a) Resource allocation problem
  - (b) Traveling salesperson problem
  - (c) Producer consumer problem
  - (d) Barber's problem

Ans: Resource allocation problem

Ans: Bubble sort.

48.	How many edges are there in a Hamil cost of cycle is 'cn'	tonian cycle if the edge cost is 'c' and the
	(a)c	(b) cn
	(c)n	(d) 2c
	Ans :n.	(a) <b>1</b>
49.	A problem L is NP-complete iff L is NP- (a) $L \approx NP$ (b) $L \alpha NP$ (c) $L \epsilon NP$ (d) $L = NP$	hard and
	Ans : L ε NP	
50.	What would be the cost value for any using branch-bound algorithm?  (a) Maximum  (b) Minimum  (c) Optimal  (d) Average	answering node of a sub tree with root 'r'
	Ans: Minimum	
51.	Name the node which has been gener been generated in state space tree of ba (a) Dead node (b) Live node (c) E-Node (d) State Node	rated but none of its children nodes have cktracking method.
	Ans: Livenode	
52.	How many nodes are there in a full stat	e space tree with n = 6?
	(a) 65	
	(b) 64	
	(c) 63	
	(d) 32	
	Ans: 63	
53.	This algorithm scans the list by swadjacent keys are out of desired order.  (a) Insertion sort.  (b) Bubble sort.  (c) Shell sort.  (d) Quick sort.	vapping the entries whenever pair of

- 54. The  $\theta$  notation is
  - (a) Symmetric
  - (b) Reflexive
  - (c) Transitive
  - (d) B & C only

**Ans: Transitive** 

- 55. From the following chose the one which belongs to the algorithm paradigm other than to which others from the following belongs to.
  - (a) Minimum & Maximum problem.
  - (b) Knapsack problem.
  - (c) Selection problem.
  - (d) Merge sort.

Ans: Knapsack problem.

- 56. To calculatec(i, j)'s, w(i, j)'s and r(i, j)'s; the OBST algorithm in worst case takes the following time.
  - (a)  $O(\log n)$
  - (b)  $O(n^4)$
  - (c)  $O(n^3)$
  - (d)  $O(n \log n)$

Ans:  $O(n^3)$ 

- 57. What is the type of the algorithm used in solving the 4 Queens problem?
  - (a) Greedy
  - (b) Dynamic
  - (c) Branch and Bound
  - (d) Backtracking.

Ans: Backtracking.

- 58.In Knapsack problem, the best strategy to get the optimal solution, where  $P_i$ ,  $W_i$  is the Profit, Weight associated with each of the  $X_i$ <sup>th</sup> object respectively is to
  - (a) Arrange the values Pi/Wi in ascending order
  - (b) Arrange the values P<sub>i</sub>/X<sub>i</sub> in ascending order
  - (c) Arrange the values Pi/Wi in descending order
  - (d) Arrange the values P<sub>i</sub>/X<sub>i</sub> in descending order

Ans: Arrange the values Pi/Xi in descending order

- 59. Greedy job scheduling with deadlines algorithms' complexity is defined as
  - (a) O(N)
  - (b)  $\Omega(n \log n)$
  - (c)  $O(n^2 \log n)$
  - (d)  $O(n \log n)$

Ans: O(N)

60 Th	a divida and	l conquer merge	cort algorithm	n's time comr	lovity can	ha dafinad ac
oo. m	e divide and	i conquer merge	SOLI AIGOLIUU	a s ume comi	nexity can	de defined as

- (a)  $\theta$  (long n)
- (b)  $\theta$  (n)
- (c)  $\Omega$  (n log n)
- (d)  $\theta$  (n log n)

Ans:  $\theta$  (n log n)

- 61. In analysis of algorithm, approximate relationship between the size of the job and the amount of work required to do it is expressed by using
  - (a) Order of magnitude or Big O
  - (b) Central tendency
  - (c) Differential equation
  - (d) Polynomial equation

Ans: Order of magnitude or Big - O

- 62. Worst case efficiency of binary search is
  - (a)  $\log_2 n + 1$
  - (b) n
  - (c)  $N^2$
  - (d)  $2^n$

Ans:  $log_2 n + 1$ 

- 63. Worst case efficiency of which search is O(n)?
  - (a) Sequential search
  - (b) Binary search
  - (c) Indexed search
  - (d) Hashing

Ans: Sequential search

- 64. Breadth first search
  - (a) Scans all incident edges before moving to other vertex
  - (b) Scans adjacentunvisited vertex as soon as possible
  - (c) Is same as backtracking
  - (d) Computes a path between two vertices of graph or equivalently

Ans: Scans all incident edges before moving to other vertex

- 65. Which of the following searching methods requires that all keys must reside in internal memory?
  - (a) Binary search
  - (b) Sequential search
  - (c) Hashing
  - (d) Depth first search

Ans: Binary search

66. Which of the following formulas in Omega notation best represent the expression

	n <sup>2</sup> +35n+6?			
	(a) $\Omega$ (n <sup>3</sup> )	(b) $\Omega$ (n <sup>2</sup> )	(c) $\Omega$ (n)	(d) $\Omega$ (35)
	Ans: $\Omega$ (n <sup>2</sup> )			
67.	What term is used	d to describe an O	O(n) algorithm?	
	(a) Constant		(b) Non Polynomia	al Deterministic
	(c) Logarithmic		(d) Linear.	
	Ans: Linear.			
68.	Express the form	ula (n - 2)*(n - 4)	using $\theta$ notation:	
	(a) $\theta$ (n <sup>2</sup> )	(b) θ (8)	(c) $\theta$ (log n)	(d) θ (n)
	Ans: $\theta$ (n <sup>2</sup> )			
69.	Read the followin	g statements car	efully and pick the ri	ght most option.
		_	olve a problem mu the same problem.	st perform faste

- er than a
  - II. An algorithm with worst case time behavior of 3n takes at least 30 operations for every input of size n=10.
    - (a) Both (I) and (II) are TRUE
    - (b) Both (I) and (II) are FALSE
    - (c) (I) is TRUE but (II) is FALSE
    - (e) (I) is FALSE and (II) is TRUE.

Ans: (I) is TRUE but (II) is FALSE

- 70. Which of the following are essential statement types for describing algorithms?
  - (a) Sequence (b) Selection (c) Repetition (d) All the above

Ans: All the above

- When we say an algorithm has a time complexity of O (n), what does it mean?
  - (a) The algorithm has 'n' nested loops
  - (b) The computation time taken by the algorithm is proportional to n
  - (c) The algorithm is 'n' times slower than a standard algorithm
  - (d) There are 'n' number of statements in the algorithm

Ans: The computation time taken by the algorithm is proportional to n

- 72. Can we read a data item at any location of a list within a constant time (i.e. O(1))?
  - (a) Yes
  - (b) Yes, only if the list is implemented by pointers (i.e. linked-list)
  - (c) Yes, only if the list is implemented by an array
  - (d) No, we need O(n) computation steps no matter what kind of implementation is used

Ans: Yes, only if the list is implemented by an array

- 73. Sequential search has a time complexity of O(n), and binary search has a time complexity of  $O(\log(n))$ . What difference will it make when the size n is 1000?
  - (a) You would not notice much difference because computers run very fast anyway
  - (b) As n is 1000, binary search is twice as fast as sequential search
  - (c) As n is 1000, binary search is 10 times as fast as sequential search
  - (d) As n is 1000, binary search is 100 times as fast as sequential search.

Ans: As n is 1000, binary search is 100 times as fast as sequential search.

- 74. Readthe following statements carefully, and choose the correct answer.
  - I. The  $\Omega$  notation is Anti Symmetric.
  - II. The big Oh notation is Semi Equivalence.
  - (a) (I) is FALSE but (II) is TRUE (b) Both (I), (II) are TRUE
  - (c) (I) is TRUE but(II) is FALSE (d) Both (I), (II) are FALSE

Ans: Both (I), (II) are TRUE

- 75. Find the odd one out.
  - (a) Merge Sort (b)TVSP Problem (c) KnapSack Problem(d) OBST Problem

Ans:Merge Sort

76. How many minimum number of spanning trees, one can have from a given connected graph with N nodes is having different weights for the edges.

(a)N-1 (b) One (c) 
$$1/(N+1)$$
 2Ncn (d) 2Ncn

Ans: one

- 77. The mathematical definition for Omega can be defined as, provided f,g:N $\rightarrow$ R+ and c is a positive constant and n > no,
  - (a)  $f(n) \ge c. g(n) n$
  - (b)  $f(n) \pm c. g(n) n$
  - (c)  $f(n) \ge c + g(n) n$
  - (d)  $f(n) \pounds c + g(n) n$
  - (e)  $f(n) \pounds g(n) n$ .

Ans: $f(n) \ge c$ . g(n) n

78.	The OBST algorithm in worst case takes calculated.		_ time if all c(i, j )'s and r(i, j)'s are
	(a) O(log n) (b) O(n4) (c) O(n3) (d) O(n	log n	1)
	Ans: O(n3)		
70	The O notation is		
79.	The $\theta$ notation is I. Symmetric.		
	II. Reflexive.		
	III. Transitive.		
	(a) Only (I) above		
	(b) Only (II) above		
	(c) Only (III) above		
	(d) All (I), (II) and (III) above.		
	Ans:All (I),(II) and (III) above.		
80.	Breadth first search uses as future processing.	s an	auxiliary structure to hold nodes fo
	(a) Stack (b) Linked list (c) Graph (d) Que	ue.	
	Ans : Queue		
81 <b>.</b> F	From the following pick the one which does no others belongs to.	t belo	ongs to the same paradigm to which
	<ul><li>(a) Minimum &amp; Maximum problem</li><li>(b) Knapsack problem</li><li>(c) Selection problem</li><li>(d) Merge sort</li></ul>		
	Ans:Knapsack problem		
82. P	Primsalgorithm is based on	metl	hod
a. b.	Divide and conquer method Greedy method	c. d.	Dynamic programming Branch and bound
Ans	s. Greedy Method		

83.	The amount of memory needs to run to	completio	n is known as
a.	Space complexity	c.	Worst case
b.	Time complexity	d.	Best case
Ans	: Space complexity		
84.	The amount of time needs to run to co	mpletion is	s known as
a.	Space complexity	с.	Worst case
b.	Time complexity	d.	Best case
Ans	: Time complexity		
85.	is the minimum number	er of steps t	hat can executed for the given
	parameters		
a.	Average case	c.	Worst case
b.	Time complexity	d.	Best case
Ans	: Best case		
86.	is the maximum number	er of steps t	that can executed for the given
	parameters		
a.	Average case	c.	Worst case
b.	Time complexity	d.	Best case
Ans	:Worst case		
87.	is the average number	of steps tha	at can executed for the given
	parameters		
a.	Average case	c.	Worst case
b.	Time complexity	d.	Best case
Ans	: Average Case		
88.	Testing of a program consists of 2 phase	ses which a	re
	and		
a.	Average case & Worst case	b. Ti	me complexity & Space complexity
c.	Validation and checking errors	d.	Debugging and profiling
Ans	: Debugging and profiling		
89.	Worst case time complexity of binary s	search is	
a.	O(n)	b.	O(logn)

c.	$\Theta(n\log n)$	d.	⊖(logn)
Ans	: Θ(logn)		
90.	Best case time complexity of binary search is	3	
a.	O(n)	c.	⊖(nlogn)
b.	O(logn)	d.	⊖(logn)
Ans	: Θ(logn)		
91.	Average case time complexity of binary search	ch is _	
a.	O(n)	c.	⊖(nlogn)
b.	O(logn)	d.	⊖(logn)
Ans	: Θ(logn)		
92.	Merge sort invented by		
a.	CARHOARE	c.	HAMILTON
b.	JOHN VON NEUMANN	d.	STRASSEN
Ans	: JOHN VON NEUMANN		
93.	Quick sort invented by		
a.	CARHOARE	c.	HAMILTON
b.	JOHN VON NEUMANN	d.	STRASSEN
Ans	: CARHOARE		
94.	Worst case time complexity of Quick sort is _		
a.	$O(n^2 \log 7)$	c.	O(nlogn)
b.	$O(n^2)$	d.	O(logn)
Ans	: O(n <sup>2</sup> )		
95.	Best case time complexity of Quick sort is		
a.	O(n²logn)	c.	O(nlogn)
b.	O(logn)	d.	O(logn <sup>2</sup> )
Ans	: O(nlogn)		
96.	Average case time complexity of Quick sort i	S	
a.	θ (nlogn)	b.	O(logn)

c. O	(nlogn) d. ⊖(logn) Ans : O(nlogn)		
	TATE: 1 1	1	·· · · · · · · · · · · · · · · · · · ·
97.	Which design strategy stops the execution we	vhen 1	it find the solution otherwise starts
	the problem from top		D
a.	Back tracking	c.	Divide and conquer
b.	Branch and Bound	d.	Dynamic programming
Ans:	Back Tracking		
98.	Graphical representation of algorithm is		
a.	Pseudo-code	c.	Graph Coloring
b.	Flow Chart	d.	Dynamic programming
Ans:	Flow Chart		
99.	In pseudo-code conventions input express a	ıs	
a.	input	c.	Read
b.	Write	d.	Return
Ans	: Write		
100.	In pseudo-code conventions output express	as	
a.	input	c.	Read
b.	Write	d.	Return
Ans	: Read		
101.	Performance based criteria of algorithm, w	hich l	nas to do with its computing time is
a.	Time Complexity	c.	Input
b.	Space Complexity	d.	Finiteness
Ans	: Time Complexity		
102.	Performance based criteria of algorithm, w	hich l	nas to do with its storage
	requirements is		
a.	Time Complexity	c.	Input
b.	Space Complexity	d.	Finiteness

103.	O(1) means computing time is		
a.	Constant	c.	Quadratic
b.	Linear	d.	Cubic
Ans	: Constant		
104.	O(n) means computing time is		
a.	Constant	c.	Quadratic
b.	Linear	d.	Cubic
Ans	: Linear		
105.	O(n <sup>2</sup> ) means computing time is		
a.	Constant	с.	Quadratic
b.	Linear	d.	Cubic
Ans	: Quadratic		
106.	O(n <sup>3</sup> ) means computing time is		
a.	Exponential	c.	Quadratic
b.	Linear	d.	Cubic
Ans	:Cubic		
107.	O(2 <sup>n</sup> ) means computing time is		
a.	Constant	с.	Quadratic
b.	Linear	d.	Exponential
Ans	: Exponential		
108.	Application of quicksort		
a.	Graphic card	c.	Data Processing
b.	Tape sorting	d.	Card Sorting
Ans	: Graphic card		
109.	Application of mergesort	-	
	Graphic card	b.	Networking

c.	Card Sorting d. Data Processing						
Ans	: Data Processing						
110.	. The method will choosing when sub problems share sub problems						
a.	Divideand conquer	c.	Greedy method				
b.	Dynamic programming d. Back tracking						
Ans	: Dynamic programming						
111.	Гime complexity of given algorithm						
Algo	rithm Display (A)						
{							
	For I:=0 to n-1						
	{						
	For J:=0 to n-1						
	{						
	Write A;						
	}						
	}						
}							
a.	2n <sup>2</sup> +4n+4	c.	2n <sup>2</sup> +n				
b.	2n <sup>2</sup> +4n+2	d.	2n <sup>2</sup> -1				
Ans	: 2n <sup>2</sup> +4n+2						
112.	The sorting, which works very well for small	file is					
a.	Count sort	c.	Selection sort				
b.	Merge sort	d.	Quick sort				
Ans:	Selection sort						
113.	Merge sort is						
a.	Externalsorting	c.	Insertion sorting				
b.	Internal sorting d. Exponential sorting						
Ans	: External sorting						
114.	is a step-by-step procedure for	calcı	ulations				

b.	Greedy Method	d.	Problem				
Ans	: Algorithm						
115.	Advantage of finding maximum and minimum using divide and conquer method instead of using conditional operators is						
a.	Reduce Space complexity	c.					
b.	Reduce Time complexity	d.	Simple calculations				
Ans	:Reduce Time complexity						
116.	Given two non-negative functions $f(n) = 5n^2$ bound value ,C	+6n+	1 and $g(n)=n^2$ . Calculate upper				
a.	C=5	c.	C=12				
b.	C=6	d.	C=11				
Ans	: C=12						
117.	Given two non-negative functions $f(n) = 6n^2 + 5n + 1$ and $g(n) = n^2$ . Calculate lower bound value ,C						
a.	C=5	c.	C=12				
b.	C=6	d.	C=11				
Ans	: C=6						
118.	The functions f &g are non-negative function	ns. T	he function $f(n)=O(g(n))$ if and only				
	if there exist positive constants c& $n_0$ such the	nat _	for all n, n≥ n₀				
a.	$f(n) \le C^*g(n)$	c.	$f(n) = C^*g(n)$				
b.	$f(n) \ge C^*g(n)$	d.	$f(n) != C^*g(n)$				
Ans	$: f(n) \le C^*g(n)$						
119.	The functions f & g are non-negative function	ns. T	the function $f(n)=\Omega(g(n))$ if and only				
	if there exist positive constants c& $n_0$ such the	nat _	for all n, n≥ n₀				
a.	$f(n) \le C^*g(n)$	c.	$f(n) = C^*g(n)$				
b.	$f(n) \ge C^*g(n)$	d.	f(n) != C*g(n)				
Ans	$: f(n) \ge C^*g(n)$						

Program

a.

Algorithm

c.

120.	The functions f & g are no	n-negative functions. The function $f(n)=\theta(g(n))$ if and only
	if there exist positive cons	tants $c_1,c_2$ & $n_0$ such thatfor all $n, n \ge n_0$
a.	$C_2*g(n) \le f(n) \le C_1*g(n)$	c. $C_2*g(n) \ge f(n) = C_1*g(n)$
b.	$C_2*g(n)!=f(n)=C_1*g(n)$	d. $C_2*g(n) \le f(n) = C_1*g(n)$
Ans	$: C_2 * g(n) \le f(n) \le C_1 * g(n)$	
121.	Tight bound is denoted as	
a.	Ω	c. Θ
b.	Ω	d. O
Ans	:Θ	
122.	Upper bound is denoted a	S
a.	Ω	с. Ө
b.	ω	d. O
Ans	: O	
123.	lower bound is denoted as	
a.	Ω	c. Θ
b.	ω	d. O
Ans	$\Omega$ :	
124.	The function $f(n)=o(g(n))$	if and only if Limit $f(n)/g(n)=on->\infty$
a.	Little oh	b. Little omega
b.	Big oh	d. Omega
Ans	: Little oh	
125.	The function $f(n) = o(g(n))$	if and only if Limit $g(n)/f(n)=0$ $n->\infty$
a.	Little oh	b. Little omega
b.	Big oh	d. Omega
Ans	: Little omega	

126.	Thegeneralcriteria of algo-	orithm;zero or more quantities are externally supplied is
a.	Output	b. Finiteness
b.	Effectiveness	d. Input
Ans	: Input	
127.	The general criteria of al	gorithm; at least one quantity is produced
a.	Output	b. Finiteness
b.	Effectiveness	d. Input
Ans	: Output	
128.	The general criteria of al	gorithm; Each instruction is clear and unambiguous
a.	Output	b. Definiteness
b.	Effectiveness	d. Input
Ans	: Definiteness	
129.	The general criteria of a	lgorithm; algorithm must terminates after a finite number
	of steps	
a.	Output	b. Finiteness
b.	Effectiveness	d. Input
Ans	: Finiteness	
130.	Which is not a criteria of	algorithm
a.	Input	b. Output
b.	Time complexity	d. Best case
Ans	: Best case	
131.	Which is not in general of	criteria of algorithm
a.	Input	b. Output
b.	Time complexity	d. Effectiveness
Ans	: Time complexity	

```
132. Time complexity of given algorithm
Algorithm Display(A)
{
     S:=0.0;
     For i:=0 to n-1
     {
            S:=S+A[i];
            Return S;
     }
}
                                                     c. 4n^2+4
a.
     4n+4
     2n<sup>2</sup>+2n+2
b.
                                                          4n+4
Ans: 4n+4
133. Time complexity of given algorithm
AlgorithmSum(A,S)
{
     for i:=1 to n-1
     {
            for j:=2 to n-1
            {
                   S:=S+i+j;
                   return S;
            }
     }
}
     6n<sup>2</sup>-14n+4
                                                          4n<sup>2</sup>+6n+12
a.
                                                     c.
     6n<sup>2</sup>+14n+10
                                                          6n<sup>2</sup>-14n+10
b.
                                                     d.
Ans:6n<sup>2</sup>-14n+10
134. kruskal algorithm is based on _____method
     Divide and conquer method
                                                          Greedy method
                                                     b.
a.
```

c. Dynamic programming

Branch and bound d.

Ans. Greedy method

- 135. Prims algorithm is based on \_\_\_\_\_ method
- Divide and conquer method a.

Dynamic programming c.

Greedy method b.

d. Branch and bound

Ans. Greedy Method

- 136. The output of Kruskal and Prims algorithm is \_\_\_
- Maximum spanning tree a.

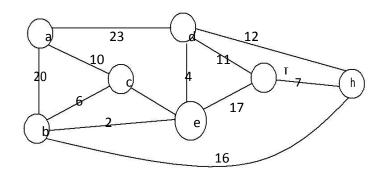
Spanning tree c.

Minimum spanning tree b.

d. None of these

Ans. Minimum spanning tree

137. Cost of minimum spanning tree , from the following diagram is \_\_\_\_\_



a. 40 41

b. 39 d. 47

Ans. 40

138. which is not feasible solution in the case of job sequence problem

27

item:

- 1
- 2
- 4

profit

100

1

- 10 15
- deadline:

3

- 2
- 2 1

a. (1,4) (4,3)

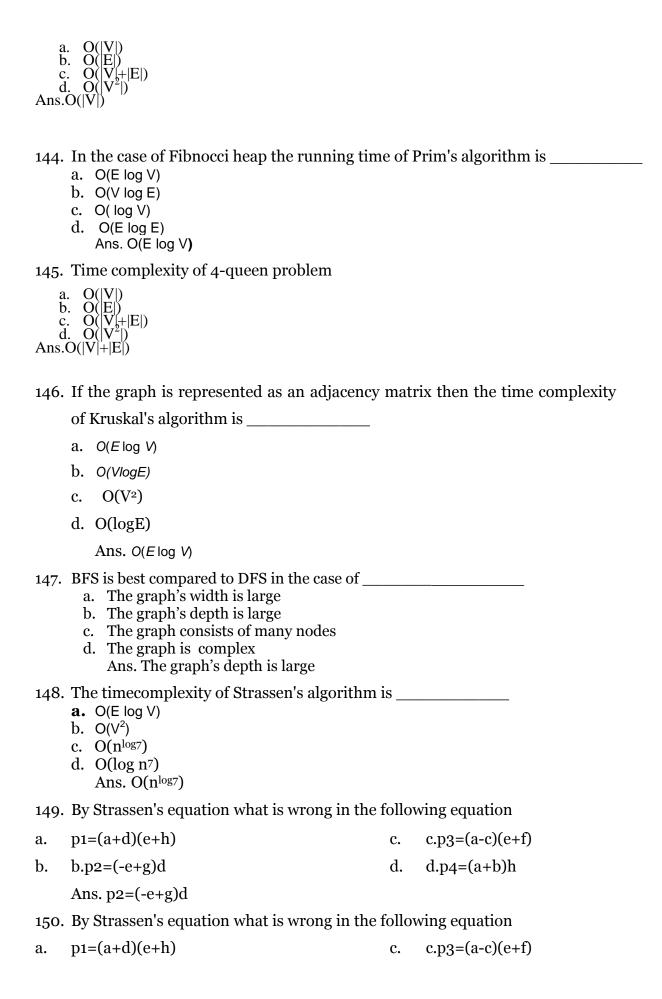
(2,4)b.

(1,2)

Ans. (2,4)

139.	which	isoptir	nal valı	ıe in tl	ne case	of job	sequ	ence	problem
item	:	1	2	3	4	5			
prof	it	:	20	15	10	5	1		
dead	lline :	2	2	3	3	3			
a.	(1,3,4)							c.	(4,2,3)
b.	(1,2,4)							d.	(1,5,2)
Ans.	(1,2,4)								
140.	which	is opti	mal val	ue in t	he case	of job	sequ	ience	problem
item	:	1	2	3	4	5	6	7	
prof	it	:	3	5	20	18	1	6	30
dead	lline :	1	3	4	3	2	1	2	
a.	(1,5,6,	4)						c.	(7,6,4,3)
b.	(2,3,1,	7)						b.	(1,2,3,4)
Ans.	(7,6,4,	3)							
141.	which	is opti	mal val	ue in tl	he case	of frac	tiona	al kna	apsack problem, capacity of
	knaps	ack is 2	20						
item	:	1	2	3					
prof	it	:	25	24	15				
weig	ht:	18	15	10					
a.	498							c.	480
b.	499							d.	485
Ans.	498								
142.	which	is opti	mal val	ue in tl	he case	of frac	tiona	al kna	apsack problem, capacity of
	knaps	ack is 1	0						
item	:	1	2	3	4	5			
prof	it	:	12	32	40	30	50		
weig	ht:	4	8	2	6	1			
a.	345							c.	384
b.	354							d.	350
Ans.	354								

143. 4 -Queen problem what is the space complexity



b.	b.p7=(-e+g)d	d.	d.p4=(a-b)h					
	Ans. p4=(a-b)h							
151.	The advantage of selecting maxmin algorithm using divide and conquer method compared to staightmaxmin algorithm is							
a.	Less time complexity	c.	High accuracy					
b.	Less space complexity	d.	High time complexity					
Ans	s. Less time complexity							
152	. The number of comparisons of e	elements for best o	case is in the case					
	of maxmin algorithm based on	divide and conque	er method					
a.	3n/2	с.	n/4					
b.	n/2	d.	n-1					
ans	. 3n/2							
153	. The number of comparisons of	elements for avera	age case is in the					
	case of maxmin algorithm based	d on divide and co	onquer method					
a.	3n/2	c.	n/4					
b.	n/2	d.	n-1					
ans	. 3n/2							
154	. The number of comparisons of $\epsilon$	elements for wors	t case is in the case					
	of maxmin algorithm based on	divide and conque	er method					
a.	3n/2	с.	n/4					
b.	n/2	d.	n-1					
ans	. 3n/2							
155.	. The method which stops the exc	ecution ,if it find t	he solution. Otherwise it start from					
	the top							
a.	Branch and bound	c.	Dynamic programming					
b.	Back tracking	d.	Divide and conquer					
Ans	s. Back tracking							
156	. Which is not return optimal sol	ution from the fol	lowing methods					
a. D	ynamic programming	с. В	c. Backtracking					
	Branch and bound	d. G	d. Greedy method					

Ans.	Backtracking		
157.	In the case of sub problems share sub problem	ns ,w	hich method is suitable
a.	greedy method	c.	branch and bound
b.	dynamic programming	d.	divide and conquer
ans.	Dynamic programming		
158.	The method which return different solutions	from	a single point ,which is
a.	greedy method	c.	branch and bound
b.	dynamic programming	d.	divide and conquer

159. ByQuicksortalgorithm from where is first partition done in the following array

ans. Greedy method

2		8	7	1	3	5	6		4	
a.	5						c.	3		
b.	4						d.	1		
Ans.	3									
_				1	1	C				
160.	Bir	npacking	gproblem	is the ap	plication	1 of				
a.	Kn	apsack					c.	Branch and bound		
b.	Ba	ck tracki	ing				d.	Dynamic programming		
Ans.	Kn	apsack								
		_								
161	ioh	seanen	cing with	deadlin	e is basec	d on			met	hod
		-	Ü	deddiiii	e is buse.	ı on				
a.	gre	eedy met	tnoa				c.	brai	nch and b	ouna
b.	dy	namic p	rogramm	ing			d.	divi	de and co	onquer
ans. Greedy method										
162.	fra	ctional l	knapsack	is based	on			_meth	od	
a.		eedy met	-				c.	braı	nch and b	ound
	0	•								

b.	dynamic programming	d.	divide and conquer
ans.	Greedy method		
163.	0/1 knapsack is based on	metho	d
a.	greedy method	c.	branch and bound
b.	dynamic programming	d.	divide and conquer
ans.	Dynamic programming		
164.	The files x1,x2,x3 are 3 files of length 30,2 merge pattern value?	20,10 rec	ords each. What is the optimal
a.	110	c.	60
b.	90	d.	50
Ans.	. 90		
165.	The optimal merge pattern is based on _		method
a.	Greedy method	b.	Dynamic programming
c.	Knapsack method	d.	Branch and bound
Ans.	. Greedy method		
166.	Who invented the word Algorithm		
a. <i>A</i>	Abu Ja'far Mohammed ibn Musa	c.	Abu Mohammed Khan
b. <i>A</i>	Abu Jafar Mohammed Kasim	d.	Abu Ja'far Mohammed Ali Khan
Ans	s. Abu Ja'far Mohammed ibn Musa		
167.	In Algorithm comments begin with		
a.	/*	c.	•
b.	*/	d.	//
Ans	s://		
168.	The of an algorithm is to completion.	he amou	ant of memory it needs to run to
a.	Space Complexity	c.	Best Case
b.	Time Complexity	d.	Worst Case
Ans	s : Space Complexity		

169.	o is the process of executing a correct program on data sets and						
	measuring the time and space it takes too	ompute	the results.				
a.	Debugging	c.	Combining				
b.	Profiling	d.	Conqure				
Ans	s : Profiling						
170.	In Algorithm Specification the blockes are	indicat	red with matching				
a. ]	Braces	c.	Square Brackets				
<b>b.</b> 1	Parenthesis	d.	Slashes				
An	as : Braces						
171.	Huffmancodes are the applications of		with minimal weighted external				
	path length obtained by an optimal set.						
a. Bs	ST	b. M	IST				
c. Bi	nary tree	d	d. Weighted Graph				
Aı	ns : Binary tree						
172.	From the following which is not return opt	imal sc	lution				
a. D	ynamic programming	c. Ba	acktracking				
b. B	ranch and bound	d. G	reedy method				
Ans.	. Backtracking						
173.	is an algorithm design	method	l that can be used when the solution				
	to a problem can be viewed as the result of	f a sequ	nence of decisions				
a. I	Dynamic programming	c. I	Backtracking				
b. E	Branch and bound	d. 0	Greedy method				
Ans	s : Dynamic programming						
174.	The name backtrack was first coined by						
a. I	O.H.Lehmer	c. I	L.Baumert				
b. F	o. R.J.Walker d. S. Golomb						
Ans	s : D.H.Lehmer						
175.	The term refers to all state spa	.ce sear	ch methods in which all hildren of				

the –no	des are generated before a	ny other live node can becomethe E-node.
a. Backtacki	ng	c. Depth First Search
b. Branch ar	nd Bound	d. Breadth First Search
Ans ; Branch	n and Bound	
176. A	is a round trip pa	th along n edges of G that visits every vertex once
and retu	ırns to its starting position	ı.
a. MST		c. TSP
b. Multistage	e Graph	d. Hamiltonian Cycle
Ans :Hamilt	onian Cycle	
177. Graph Co a. Backtacki	oloring is which type of alg	gorithm design strategy c. Greedy
b. Branch aı	nd Bound	d. Dynamic programming
Ans : Backtı	racking	
178. Which o	of the following is not a lim	nitation of binary search algorithm?
a. must use	a sorted array	
b. requirements	_	ensive when a lot of insertion and deletions
c. there mus	st be a mechanism to acces	ss middle element directly
d. binary sea	arch algorithm is not effici	ient when the data elements are more than 1000.
Ans : binary	search algorithm is not ef	fficient when the data elements are more than 1000
179. Binary S	Search Algorithm cannot b	e applied to
a. Sorted lin	ıked list	c. Sorted linear array
b. Sorted bi	nary tree	d. Pointer array
Ans :Sorted	linked list	
180. Two mai	in measures for the efficien	ncy of an algorithm are
a. Processor	and memory	c. Time and space
b. Complexi	ty and capacity	d. Data and space
Ans : Time a	and Space	

181. The time factor when determining the efficiency of algorithm is measured by

a. Counting microseconds

c. Counting the number of statements

b. Counting the number of key

d. Counting the kilobytes of algorithm

operations

Ans: Counting the number of key operations

182. The space factor when determining the efficiency of algorithm is measured by

- a. Counting the maximum memory needed by the algorithm
- b. Counting the minimum memory needed by the algorithm
- c. Counting the average memory needed by the algorithm
- d. Counting the maximum disk space needed by the algorithm Ans: Counting the maximum memory needed by the algorithm

183. Which of the following case does not exist in complexity theory

a. Best case

c. Average case

b. Worst case

d. Null case

Ans: Null Case

184. The Worst case occur in linear search algorithm when

a. Item is somewhere in the middle of c. Item is the last element in the array

the array

d. Item is the last element in the array

b. Item is not in the array at all

or is not there at all

Ans: Item is the last element in the array or is not there at all

185. The Average case occur in linear search algorithm

a. When Item is somewhere in the middle of the array

c. When Item is the last element in the

array

b. When Item is not in the array at all d. When Item is the last element in the

array or is not there at all

Ans: When Item is somewhere in the middle of the array

186. The complexity of the average case of an algorithm is

a. Much more complicated to analyze

c. Sometimes more complicated and

than that of worst case

some other times simpler than that of

b. Much more simpler to analyze than worst case

that of worst case

d. None or above

Ans: Much more complicated to analyze than that of worst case

187. The complexity of linear search algorithm is

a. O(n) c. O(n2)

b.  $O(\log n)$  d.  $O(n \log n)$ 

Ans: O(n)

188. The complexity of Binary search algorithm is

a. O(n) c. O(n2)

b.  $O(\log n)$  d.  $O(n \log n)$ 

Ans: O(log n)

189. The complexity of Bubble sort algorithm is

a. O(n) c.  $O(n^2)$ 

b.  $O(\log n)$  d.  $O(n \log n)$ 

Ans:  $O(n^2)$ 

190. The complexity of merge sort algorithm is

a. O(n) c. O(n2)

b.  $O(\log n)$  d.  $O(n \log n)$ 

Ans:  $O(n \log n)$ 

191. Which of the following sorting algorithm is of divide-and-conquer type?

a. Bubble sort c. Quick sort

b. Insertion sort d. All of above

Ans: Quick Sort

192. An algorithm that calls itself directly or indirectly is known as

a. Sub algorithm c. Polish notation

b. Recursion d. Traversal algorithm

Ans: Recursion

- 193. The running time of quick sort depends heavily on the selection of
  - a. No of inputs

- c. Size o elements
- b. Arrangement of elements in array
- d. Pivot element

Ans: Pivot Element

194. In stable sorting algorithm

a. One array is used

- c. More then one arrays are required.
- b. In which duplicating elements are not handled.
- d. Duplicating elements remain in same relative position after sorting.

Ans:Duplicating elements remain in same relative position after sorting.

195. Which sorting algorithm is faster:

a. O(n^2)

c. O(n+k)

b. O(nlogn)

d. O(n^3)

Ans :O(n+k)

- 196. In Quick sort algorithm, constants hidden in T(n lg n) are
  - a. Large

c. Not known

b. Medium

d. Small

Ans: Small

- 197. Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivotelementand:
  - a. There is explicit combine process as well to conquer the solution.
  - b. No work is needed to combine the sub-arrays, the array is already sorted
  - c. Merging the subarrays
  - d. None of above.

Ans: There is explicit combine process as well to conquer the solution.

## 198. Dijkstra's algorithm:

- a. Has greedy approach to find all shortest paths
- b. Has both greedy and Dynamic approach to find all shortest paths
- c. Has greedy approach to compute single source shortest paths to all other vertices
- d. Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

Ans: Has greedy approach to compute single source shortest paths to all other vertices

- 199. What algorithm technique is used in the implementation of Kruskal's solution for the MST?
  - a. Greedy Technique
  - b. Divide-and-ConquerTechnique
  - c. Dynamic Programming Technique
  - d. The algorithm combines more than one of the above techniques

Ans:Greedy Technique

200. Which is true statement in the following?

- a. Kruskal'salgorithm is multiple source technique for finding MST.
- b. Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is O(EV)
- c. Both of above
- d. Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best Tree edge) when the graph has relatively few edges )

Ans:Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best Tree edge) when the graph has relatively few edges )